Based on Form PTO-1449 (3/90)	ATTY. DOCKET NO. 450100-02856.2	SERIAL NO. 10/775,845 Filed Concurrently Herewith
LIST OF REFERENCES CITED BY APPLICANT (Use several sheets if necessary)	APPLICANT Yuichi HATTORI et al.	
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EXAMINER INITIAL		DOCUMENT NUMBER	DATE	NAME	CLASS	SUBCLASS	FILING DATE IF APPROPRIATE
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	AB	5,737,217	4/98	Nishikawa et al.	180	8.6	
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m.m	AU		~~Microfilm of the specification and drawings annexed to the request of Japanese Utility Model~~ Application No. 63-85017 (Laid-open No. 2-8498)
	AV		INABA M ET AL: "TWO-ARMED BIPEDAL ROBOT THAT CAN WALK, ROLL OVER AND STAND UP" PROCEEDINGS. 1995 IEEE/RSJ INTERNATIONAL CONFERENCE ON INTELLIGENT ROBOTS AND SYSTEMS. HUMAN ROBOT INTERACTION AND COOPERATIVE ROBOTS (CAT. NO. 95CB35836), PROCEEDINGS 1995 IEEE/RSJ INTERNATIONAL CONFERENCE ON INTELLIGENT ROBOTS AND SYSTEMS. HUMAN ROB, PAGES 297-302, VOL. 3, XP002164248 1995, LOS ALAMITOS, CA, USA, IEEE COMPUT. SOC. PRESS, USA
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EXAMINER	DATE CONSIDERED
Marc Jeanmarc	4-18-05

* EXAMINER: Initial if reference considered, whether or not citation is in conformance with MPEP 609. Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.